

<b>Notice of References Cited</b>	Application/Control No. 10/596,055		Applicant(s)/Patent Under Reexamination TAKENAKA ET AL.	
	Examiner MCDIEUNEL MARC		Art Unit 3664	Page 1 of 1

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*	B	US-7,339,340	03-2008	Summer et al.	318/568.12
*	C	US-4,662,465	05-1987	Stewart, David E. S.	180/8.1
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	W	Youcef et al., Control of the trajectory of a hexapod robot based on distributed Q-learning, 2004, IEEE, pg. 277-282
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\*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).)  
Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.